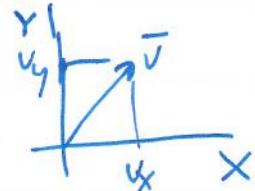


## VECTORS

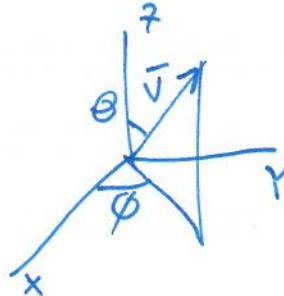
### Basics

$$\vec{v} = \vec{v}_x + \vec{v}_y = v_x \vec{i} + v_y \vec{j}$$

2D  $\begin{cases} v_x = v \cos \theta \\ v_y = v \sin \theta \end{cases}$

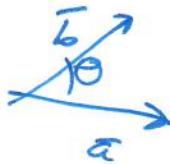


3D  $\begin{cases} v_x = v \sin \theta \cos \phi \\ v_y = v \sin \theta \sin \phi \\ v_z = v \cos \theta \end{cases}$



### Dot product

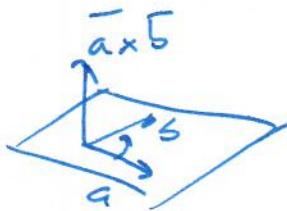
$$\vec{a} \cdot \vec{b} = a_x b_x + a_y b_y + a_z b_z \\ = |a| |b| \cos \theta$$



Meaning  
↓ projection

### Cross product

$$\vec{a} \times \vec{b}$$



$$\vec{a} \times \vec{b} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ a_x & a_y & a_z \\ b_x & b_y & b_z \end{vmatrix}$$

$$|\vec{a} \times \vec{b}| = |a| |b| \sin \theta$$

### Angle

$$\frac{\theta}{R} l$$

$$\theta = \frac{l}{R}$$

$$\frac{\theta}{R} dl$$

$$d\theta = \frac{dl}{R}$$

### Solid Angle



$$d\Omega = \frac{dS}{R^2}$$

$$d\Omega = \frac{dS}{R^2}$$

## Surfaces as vectors



$$\vec{S} = \vec{S}/|\vec{S}|$$

$$\vec{S} = \int d\vec{S} = \int dS' \vec{n}$$

## Line Integral

$$I = \int_r \vec{v} \cdot d\vec{l}$$



$C$  = path

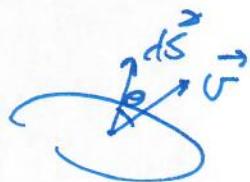
Example: work

Circulation  $C$  is a closed path

$$C = \oint \vec{v} \cdot d\vec{l}$$

## Flux

$$\Phi = \int \vec{v} \cdot d\vec{S}$$



$$\left\{ \begin{array}{l} \text{Max : } \theta = 0 \\ \text{Min : } \theta = \frac{\pi}{2} \end{array} \right.$$

## Nabla operator

$$\bar{\nabla} = \left( \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right)$$

## Divergence

$$\bar{\nabla} \cdot \vec{v} = \left( \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right) (v_x, v_y, v_z)$$

$$= \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z}$$

## Gradient

$$\bar{\nabla} \cdot \vec{q} = \left( \frac{\partial \phi}{\partial x}, \frac{\partial \phi}{\partial y}, \frac{\partial \phi}{\partial z} \right)$$

## Curl

$$\bar{\nabla} \times \vec{v} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_x & v_y & v_z \end{vmatrix}$$

## Divergence theorem / Gauss theorem

$$\oint \vec{v} \cdot d\vec{s} = \iiint_V (\bar{\nabla} \cdot \vec{v}) dV$$

## Stokes theorem

$$\oint \vec{v} \cdot d\vec{l} = \iint_S (\bar{\nabla} \times \vec{v}) d\vec{s}$$

$$\text{Conservative field} \Rightarrow (\bar{\nabla} \times \vec{v}) = 0$$